## CS 188: Artificial Intelligence

## Bayes' Nets: Inference



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## Bayes' Nets

- Representation

Conditional Independences

- Probabilistic Inference
- Enumeration (exact, exponential complexity)
- Variable elimination (exact, worst-case exponential complexity, often better)
- Inference is NP-complete
- Sampling (approximate)
- Learning Bayes' Nets from Data


## Bayes' Net Representation

- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
- A collection of distributions over $X$, one for each combination of parents' values

$$
P\left(X \mid a_{1} \ldots a_{n}\right)
$$

- Bayes' nets implicitly encode joint distributions

- As a product of local conditional distributions
- To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$
P\left(x_{1}, x_{2}, \ldots x_{n}\right)=\prod_{i=1}^{n} P\left(x_{i} \mid \text { parents }\left(X_{i}\right)\right)
$$



## Example: Alarm Network



| $E$ | $P(E)$ |
| :---: | :---: |
| $+e$ | 0.002 |
| $-e$ | 0.998 |



| $B$ | $E$ | $A$ | $P(A \mid B, E)$ |
| :---: | :---: | :---: | :---: |
| $+b$ | $+e$ | $+a$ | 0.95 |
| $+b$ | $+e$ | $-a$ | 0.05 |
| $+b$ | $-e$ | $+a$ | 0.94 |
| $+b$ | $-e$ | $-a$ | 0.06 |
| $-b$ | $+e$ | $+a$ | 0.29 |
| $-b$ | $+e$ | $-a$ | 0.71 |
| $-b$ | $-e$ | $+a$ | 0.001 |
| $-b$ | $-e$ | $-a$ | 0.999 |

## Example: Alarm Network

| $B$ | $P(B)$ |
| :---: | :---: |
| $+b$ | 0.001 |
| $-b$ | 0.999 |


$P(+b,-e,+a,-j,+m)=$
$P(+b) P(-e) P(+a \mid+b,-e) P(-j \mid+a) P(+m \mid+a)=$

| $B$ | $E$ | $A$ | $P(A \mid B, E)$ |
| :---: | :---: | :---: | :---: |
| $+b$ | $+e$ | $+a$ | 0.95 |
| $+b$ | $+e$ | $-a$ | 0.05 |
| $+b$ | $-e$ | $+a$ | 0.94 |
| $+b$ | $-e$ | $-a$ | 0.06 |
| $-b$ | $+e$ | $+a$ | 0.29 |
| $-b$ | $+e$ | $-a$ | 0.71 |
| $-b$ | $-e$ | $+a$ | 0.001 |
| $-b$ | $-e$ | $-a$ | 0.999 |

## Example: Alarm Network

| $B$ | $P(B)$ |
| :---: | :---: |
| $+b$ | 0.001 |
| $-b$ | 0.999 |



| $A$ | $J$ | $P(J \mid A)$ |
| :---: | :---: | :---: |
| +a | +j | 0.9 |
| +a | -j | 0.1 |
| -a | +j | 0.05 |
| -a | -j | 0.95 |

$P(+b,-e,+a,-j,+m)=$
$P(+b) P(-e) P(+a \mid+b,-e) P(-j \mid+a) P(+m \mid+a)=$
$0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7$

| $B$ | $E$ | $A$ | $P(A \mid B, E)$ |
| :---: | :---: | :---: | :---: |
| $+b$ | $+e$ | $+a$ | 0.95 |
| $+b$ | $+e$ | $-a$ | 0.05 |
| $+b$ | $-e$ | $+a$ | 0.94 |
| $+b$ | $-e$ | $-a$ | 0.06 |
| $-b$ | $+e$ | $+a$ | 0.29 |
| $-b$ | $+e$ | $-a$ | 0.71 |
| $-b$ | $-e$ | $+a$ | 0.001 |
| $-b$ | $-e$ | $-a$ | 0.999 |

## Bayes' Nets

## Representation

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## Inference

- Inference: calculating some useful quantity from a joint probability distribution
- Examples:
- Posterior probability

$$
P\left(Q \mid E_{1}=e_{1}, \ldots E_{k}=e_{k}\right)
$$

- Most likely explanation:

$$
\operatorname{argmax}_{q} P\left(Q=q \mid E_{1}=e_{1} \ldots\right)
$$



## Inference by Enumeration

- General case:
- Evidence variables:
- Query* variable:
- Hidden variables:
- We want:
* Works fine with multiple query
variables, too

$$
P\left(Q \mid e_{1} \ldots e_{k}\right)
$$

- Step 3: Normalize of Query and evidence


$$
P\left(Q, e_{1} \ldots e_{k}\right)=\sum_{h_{1} \ldots h_{r}} P(\underbrace{Q, h_{1} \ldots h_{r}, e_{1} \ldots e_{k}}_{X_{1}, X_{2}, \ldots X_{n}})
$$

## Inference by Enumeration in Bayes' Net

- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:

$$
P(B \mid+j,+m) \propto_{B} P(B,+j,+m)
$$

$$
=\sum_{e, a} P(B, e, a,+j,+m)
$$

$$
=\sum_{e, a} P(B) P(e) P(a \mid B, e) P(+j \mid a) P(+m \mid a)
$$



$$
\begin{aligned}
= & P(B) P(+e) P(+a \mid B,+e) P(+j \mid+a) P(+m \mid+a)+P(B) P(+e) P(-a \mid B,+e) P(+j \mid-a) P(+m \mid-a) \\
& P(B) P(-e) P(+a \mid B,-e) P(+j \mid+a) P(+m \mid+a)+P(B) P(-e) P(-a \mid B,-e) P(+j \mid-a) P(+m \mid-a)
\end{aligned}
$$

## Inference by Enumeration?


$P($ Antilock $\mid$ observed variables $)=?$

## Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
- You join up the whole joint distribution before you sum out the hidden variables
- Idea: interleave joining and marginalizing!
- Called "Variable Elimination"
- Still NP-hard, but usually much faster than inference by enumeration

- First we'll need some new notation: factors

Factor Zoo


## Factor Zoo I

- Joint distribution: $P(X, Y)$
- Entries $P(x, y)$ for all $x, y$
- Sums to 1

$$
P(T, W)
$$

| $T$ | $W$ | $P$ |
| :---: | :---: | :---: |
| hot | sun | 0.4 |
| hot | rain | 0.1 |
| cold | sun | 0.2 |
| cold | rain | 0.3 |

- Selected joint: $\mathrm{P}(\mathrm{x}, \mathrm{Y})$
- A slice of the joint distribution
- Entries $\mathrm{P}(\mathrm{x}, \mathrm{y})$ for fixed x , all y
- Sums to $\mathrm{P}(\mathrm{x})$

| $P($ cold,$W)$ |
| :--- |
| T |
| W |
| cold |
| cold |
| sun |

- Number of capitals = dimensionality of the table



## Factor Zoo II

- Single conditional: $P(Y \mid x)$
- Entries $P(y \mid x)$ for fixed $x$, all
- Sums to 1

$P(W \mid$ cold $)$

| T | W | P |
| :---: | :---: | :---: |
| cold | sun | 0.4 |
| cold | rain | 0.6 |

- Family of conditionals: $P(X \mid Y)$
- Multiple conditionals
- Entries $P(x \mid y)$ for all $x, y$
- Sums to $|\mathrm{Y}|$



## Factor Zoo III

- Specified family: $P(y \mid X)$
- Entries P(y|x) for fixed $y$, but for all x
- Sums to ... who knows!
$P(\operatorname{rain} \mid T)$
\(\left.\begin{array}{|c|c|c|}\hline \mathrm{T} \& \mathrm{W} \& \mathrm{P} <br>
\hline hot \& rain \& 0.2 <br>
\hline cold \& rain \& 0.6 <br>

\hline\end{array}\right\}\)| $P($ rain $\mid$ hot $)$ |
| :--- |
| $P($ rain $\mid$ cold $)$ |



## Factor Zoo Summary

- In general, when we write $P\left(Y_{1} \ldots Y_{N} \mid X_{1} \ldots X_{M}\right)$
- It is a "factor," a multi-dimensional array
- Its values are $P\left(y_{1} \ldots y_{N} \mid x_{1} \ldots x_{M}\right)$
- Any assigned (=lower-case) $X$ or $Y$ is a dimension missing (selected) from the array



## Example: Traffic Domain

- Random Variables
- R: Raining
- T: Traffic
- L: Late for class!

$$
\begin{aligned}
P(L) & =? \\
& =\sum_{r, t} P(r, t, L) \\
& =\sum_{r, t} P(r) P(t \mid r) P(L \mid t)
\end{aligned}
$$

$P(R)$

| $+r$ | 0.1 |
| :---: | :---: |
| $-r$ | 0.9 |


| $P(T \mid R)$ |  |  |
| :--- | :---: | :---: |
| +r |  |  |
| +t 0.8  <br> +r -t 0.2 <br> -r +t 0.1 <br> -r -t 0.9 |  |  |


| $P(L \mid T)$ |  |  |
| :---: | :---: | :---: |
| +t | +1 | 0.3 |
| +t | - | 0.7 |
| -t | +1 | 0.1 |
| -t | -1 | 0.9 |

## Inference by Enumeration: Procedural Outline

- Track objects called factors
- Initial factors are local CPTs (one per node)

| $P(R)$ |  | $P(T \mid R)$ |  |  | $P(L \mid T)$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| +r | 0.1 | +r | +t | 0.8 | +t | +1 | 0.3 |
| -r | 0.9 | +r | -t | 0.2 | +t | -1 | 0.7 |
|  |  | -r | +t | 0.1 | -t | +1 | 0.1 |
|  |  | -r | -t | 0.9 | -t | - | 0.9 |

- Any known values are selected
- E.g. if we know $L=+\ell$, the initial factors are
$P(R)$

| $+r$ | 0.1 |
| :---: | :---: |
| $-r$ | 0.9 |

$P(T \mid R)$

| $+r$ | $+t$ | 0.8 |
| :---: | :---: | :---: |
| $+r$ | $-t$ | 0.2 |
| $-r$ | $+t$ | 0.1 |
| $-r$ | $-t$ | 0.9 |

$$
\begin{aligned}
& P(+\ell \mid T) \\
& \begin{array}{|c|c|c|}
\hline+\mathrm{t} & +\mathrm{l} & 0.3 \\
\hline-\mathrm{t} & +\mathrm{l} & 0.1 \\
\hline
\end{array}
\end{aligned}
$$



- Procedure: Join all factors, then eliminate all hidden variables


## Operation 1: Join Factors

- First basic operation: joining factors
- Combining factors:
- Just like a database join
- Get all factors over the joining variable
- Build a new factor over the union of the variables
 involved
- Example: Join on R

- Computation for each entry: pointwise products

$$
\forall r, t: \quad P(r, t)=P(r) \cdot P(t \mid r)
$$

Example: Multiple Joins

$\Rightarrow$


## Example: Multiple Joins


$P(R)$


## Operation 2: Eliminate

- Second basic operation: marginalization
- Take a factor and sum out a variable
- Shrinks a factor to a smaller one
- A projection operation
- Example:
$P(R, T)$

| $+r$ | +t | 0.08 |
| :---: | :---: | :---: |
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |


| sum $R$ | $P(T)$ |  |
| :---: | :---: | :---: |
| $\square$ | +t 0.17 <br> -t 0.83 |  |

## Multiple Elimination



Thus Far: Multiple Join, Multiple Eliminate (= Inference by Enumeration)


## Marginalizing Early (= Variable Elimination)



## Traffic Domain

## (R) $\quad P(L)=$ ?

- Inference by Enumeration

$$
=\sum_{t} \sum_{r} P(L \mid t) \underbrace{P(r) P(t \mid r)}_{\text {Join on } \mathrm{r}}
$$



Eliminate r

Eliminate t

- Variable Elimination

$$
=\sum_{t} P(L \mid t) \sum_{r} P(r) P(t \mid r)
$$



Eliminate t

## Marginalizing Early! (aka VE)



## Evidence

- If evidence, start with factors that select that evidence
- No evidence uses these initial factors:

| $P(R)$ |  |
| :--- | :---: |
| $+r$ 0.1 <br> $-r$ 0.9 |  |


| $P($ |  |  |
| :---: | :---: | :---: |
|  | + | 0.8 |
|  |  |  |
|  | +t | 0.1 |
|  |  |  |

$$
P(L \mid T)
$$

| +t | +l | 0.3 |
| :---: | :---: | :---: |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

- Computing $P(L \mid+r)$ the initial factors become:

| $P(+r)$ |  |
| :---: | :---: |
| $+r \mid 0.1$ |  |

$$
\begin{gathered}
P(T \mid+r) \\
\begin{array}{c|c|c|}
\hline+r & +1 & 0.8 \\
\hline+r & -\mathrm{t} & 0.2 \\
\hline
\end{array}
\end{gathered}
$$

$P(L \mid T)$

| +t | +l | 0.3 |
| :---: | :---: | :---: |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

- We eliminate all vars other than query + evidence



## Evidence II

- Result will be a selected joint of query and evidence
- E.g. for $P(L \mid+r)$, we would end up with:

| $P(+r, L)$ |  |  | Normalize | $P(L \mid+r)$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| +r | +1 | 0.026 |  | +1 | 0.26 |
| +r | -1 | 0.074 |  | - | 0.74 |

- To get our answer, just normalize this!
- That's it!



## General Variable Elimination

- Query: $P\left(Q \mid E_{1}=e_{1}, \ldots E_{k}=e_{k}\right)$
- Start with initial factors:
- Local CPTs (but instantiated by evidence)



## Example

$$
P(B \mid j, m) \propto P(B, j, m)
$$

$$
P(B) \quad P(E) \quad P(A \mid B, E) \quad P(j \mid A) \quad P(m \mid A)
$$



Choose A

$$
\begin{aligned}
& P(A \mid B, E) \\
& P(j \mid A) \\
& P(m \mid A)
\end{aligned} \quad \boxed{\times} P(j, m, A \mid B, E) \quad \underset{ }{\sum} P(j, m \mid B, E)
$$

$$
P(B) \quad P(E) \quad P(j, m \mid B, E)
$$

## Example

$$
P(B) \quad P(E) \quad P(j, m \mid B, E)
$$

Choose E

$$
\begin{array}{ccc}
P(E) \\
P(j, m \mid B, E) & \boxed{\times} P(j, m, E \mid B) \quad \underset{\sum}{ } P(j, m \mid B) .
\end{array}
$$

$P(B) \quad P(j, m \mid B)$

Finish with B

$$
\begin{array}{lll}
P(B) \\
P(j, m \mid B) & \square \times & P(j, m, B) \xrightarrow{\text { Normalize }} P(B \mid j, m)
\end{array}
$$

## Same Example in Equations

$$
P(B \mid j, m) \propto P(B, j, m)
$$

$P(B) \quad P(E) \quad P(A \mid B, E) \quad P(j \mid A) \quad P(m \mid A)$

$$
\begin{aligned}
P(B \mid j, m) & \propto P(B, j, m) \\
& =\sum_{e, a} P(B, j, m, e, a) \\
& =\sum_{e, a} P(B) P(e) P(a \mid B, e) P(j \mid a) P(m \mid a) \\
& =\sum_{e} P(B) P(e) \sum_{a} P(a \mid B, e) P(j \mid a) P(m \mid a) \\
& =\sum_{e} P(B) P(e) f_{1}(B, e, j, m) \\
& =P(B) \sum_{e} P(e) f_{1}(B, e, j, m) \\
& =P(B) f_{2}(B, j, m)
\end{aligned}
$$


marginal can be obtained from joint by summing out use Bayes' net joint distribution expression
use $x^{*}(y+z)=x y+x z$
joining on $a$, and then summing out gives $f_{1}$
use $x^{*}(y+z)=x y+x z$
joining on $e$, and then summing out gives $f_{2}$

## Another Variable Elimination Example

$$
\text { Query: } P\left(X_{3} \mid Y_{1}=y_{1}, Y_{2}=y_{2}, Y_{3}=y_{3}\right)
$$

Start by inserting evidence, which gives the following initial factors:

$$
p(Z) p\left(X_{1} \mid Z\right) p\left(X_{2} \mid Z\right) p\left(X_{3} \mid Z\right) p\left(y_{1} \mid X_{1}\right) p\left(y_{2} \mid X_{2}\right) p\left(y_{3} \mid X_{3}\right)
$$

Eliminate $X_{1}$, this introduces the factor $f_{1}\left(Z, y_{1}\right)=\sum_{x_{1}} p\left(x_{1} \mid Z\right) p\left(y_{1} \mid x_{1}\right)$, and we are left with:

$$
p(Z) f_{1}\left(Z, y_{1}\right) p\left(X_{2} \mid Z\right) p\left(X_{3} \mid Z\right) p\left(y_{2} \mid X_{2}\right) p\left(y_{3} \mid X_{3}\right)
$$



Eliminate $X_{2}$, this introduces the factor $f_{2}\left(Z, y_{2}\right)=\sum_{x_{2}} p\left(x_{2} \mid Z\right) p\left(y_{2} \mid x_{2}\right)$, and we are left with:

$$
p(Z) f_{1}\left(Z, y_{1}\right) f_{2}\left(Z, y_{2}\right) p\left(X_{3} \mid Z\right) p\left(y_{3} \mid X_{3}\right)
$$

Eliminate $Z$, this introduces the factor $f_{3}\left(y_{1}, y_{2}, X_{3}\right)=\sum_{z} p(z) f_{1}\left(z, y_{1}\right) f_{2}\left(z, y_{2}\right) p\left(X_{3} \mid z\right)$, and we are left:

$$
p\left(y_{3} \mid X_{3}\right), f_{3}\left(y_{1}, y_{2}, X_{3}\right)
$$

No hidden variables left. Join the remaining factors to get:

$$
f_{4}\left(y_{1}, y_{2}, y_{3}, X_{3}\right)=P\left(y_{3} \mid X_{3}\right) f_{3}\left(y_{1}, y_{2}, X_{3}\right) .
$$

Normalizing over $X_{3}$ gives $P\left(X_{3} \mid y_{1}, y_{2}, y_{3}\right)$.

## Variable Elimination Ordering

- For the query $\mathrm{P}\left(\mathrm{X}_{\mathrm{n}} \mid \mathrm{y}_{1}, \ldots, \mathrm{y}_{\mathrm{n}}\right)$ work through the following two different orderings as done in previous slide: $Z, X_{1}, \ldots, X_{n-1}$ and $X_{1}, \ldots, X_{n-1}, Z$. What is the size of the maximum factor generated for each of the orderings?

- Answer: $2^{n+1}$ versus $2^{2}$ (assuming binary)
- In general: the ordering can greatly affect efficiency.


## VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
- E.g., previous slide's example $2^{n}$ vs. 2
- Does there always exist an ordering that only results in small factors?
- No!


## Worst Case Complexity?

- CSP:
$\left(x_{1} \vee x_{2} \vee \neg x_{3}\right) \wedge\left(\neg x_{1} \vee x_{3} \vee \neg x_{4}\right) \wedge\left(x_{2} \vee \neg x_{2} \vee x_{4}\right) \wedge\left(\neg x_{3} \vee \neg x_{4} \vee \neg x_{5}\right) \wedge\left(x_{2} \vee x_{5} \vee x_{7}\right) \wedge\left(x_{4} \vee x_{5} \vee x_{6}\right) \wedge\left(\neg x_{5} \vee x_{6} \vee \neg x_{7}\right) \wedge\left(\neg x_{5} \vee \neg x_{6} \vee x_{7}\right)$

$$
\begin{aligned}
& P\left(X_{i}=0\right)=P\left(X_{i}=1\right)=0.5 \\
& Y_{1}=X_{1} \vee X_{2} \vee \neg X_{3} \\
& \cdots \\
& Y_{8}=\neg X_{5} \vee X_{6} \vee X_{7} \\
& Y_{1,2}=Y_{1} \wedge Y_{2} \\
& Y_{7,8}=Y_{7} \wedge Y_{8} \\
& Y_{1,2,3,4}=Y_{1,2} \wedge Y_{3,4} \\
& Y_{5,6,7,8}=Y_{5,6} \wedge Y_{7,8} \\
& Z=Y_{1,2,3,4} \wedge Y_{5,6,7,8}
\end{aligned}
$$



- If we can answer $\mathrm{P}(\mathrm{z})$ equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.


## Polytrees

- A polytree is a directed graph with no undirected cycles
- For poly-trees you can always find an ordering that is efficient
- Try it!!
- Cut-set conditioning for Bayes' net inference
- Choose set of variables such that if removed only a polytree remains
- Exercise: Think about how the specifics would work out!


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$\downarrow$ Inference is NP-complete
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